

SPECIFICATION ANALYSIS OF DIFFUSION MODELS FOR THE ITALIAN SHORT RATE

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ABSTRACT. In recent years, diffusion models for interest rates became very popular. In this paper, we perform a selection of a suitable diffusion model for the Italian short rate. Our data set is given by the yields on three-month BOT (*Buoni Ordinari del Tesoro*), from 1981 to 2001, for a total of 470 observations. We investigate among stochastic volatility models, paying more attention to affine models. Estimating diffusion models via maximum likelihood, which would lead to efficiency, is usually unfeasible since the transition density is not available. Recently it has been proposed a method of moments which gains full efficiency, hence its name of Efficient Method of Moments (EMM); it selects the moments as the scores of an auxiliary model, to be computed via simulation, thus EMM is suitable to diffusions whose transition density is unknown, but which are convenient to simulate. The auxiliary model is selected among a family of densities which spans the density space. As a by-product, EMM provides diagnostics which are easy to compute and to interpret. We find evidence that one-factor models and multi-factor affine models are rejected, while a logarithmic specification of the volatility provides the best fit to the data.

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1. INTRODUCTION AND MOTIVATION

The modeling of the term structure of interest rates is one of the most challenging research area in finance. It is nowadays common to model the term structure by specifying the evolution of one primary state variable, the inherently unobservable short, or instantaneous, or spot rate, which is allowed to depend on a given number of state variables, typically Markov-type continuous time diffusions. If we denote by Y_t the \mathbb{R}^d -vector of state variables, one of them being the spot rate, we model its diffusion process as:

$$(1.1) \quad dY_t = \mu(Y_t, t; \rho)dt + \sigma(Y_t, t; \rho)dW_t,$$

where $\mu(Y_t, t; \rho)$ and $\sigma(Y_t, t; \rho)$ are respectively the drift and the diffusion of the process, while W_t is a standard d -dimensional Brownian motion. The only condition on the functions μ and σ is that they are such that a strong solution of (1.1) exists. Such models are typically parametric models, i.e. they depend on a given set of parameters ρ . In recent years, much complicated interest rate models have been proposed in this framework in order to deal with the observed empirical facts. This development led to increasing sophistication of econometric techniques to estimate these increasingly complex models¹. The motivation underlying the need for sophistication is the following: the general representation (1.1) is a continuous-time representation, while observations are discretely sampled, e.g. in the form of fixed (daily, monthly) time-span interval data. Thus, if we denote by $\{P_t(Y_t), t = 1, \dots, n\}$ the size- n observation set, given the functions $\mu(Y_t, t; \rho), \sigma(Y_t, t; \rho)$ the parameter vector ρ could, in principle, be estimated by maximum likelihood via the evaluation of the transition density in the observed data points; as it is well known, such a procedure would lead to the most efficient estimate. Unfortunately, with the exception of few not very flexible models, the transition density of the process (1.1) is generally not analytically computable, and even very difficult to compute numerically, thus efficient estimation cannot be achieved by this standard technique².

¹Chapman and Pearson (2001) provide a review of the recent advancements in this field, while Sundaresan (2000) reviews the benefits of using continuous-time models in many fields of finance, among which interest rate modeling.

²A relevant exception to this rule is provided by affine models (Duffie and Kan, 1996). For affine models, the transition density can be computed via the inversion of the characteristic function (Singleton, 2001), which has a convenient exponential-affine representation, with the only problem of the curse of dimensionality. An example of this technique is provided in Mari and Renò (2005).

To circumvent this difficulty, many techniques have been proposed in the literature. Ait-Sahalia (1996) and Stanton (1997) approximate the transition density via non-parametric densities, which asymptotically span the true density; Christensen et al. (2001) provide numerical recipes to solve the PDE associated with the likelihood function; Brandt and Santa-Clara (2002) and Pedersen (1995) compute the transition density via simulation; Jacquier et al. (1994); Elerian et al. (2001); Eraker (2001) adopt a Bayesian methodology. All these methods approximate the true transition density in some way, thus achieving efficiency asymptotically, but their finite-sample properties are largely unknown; moreover, they are often computationally intensive, sometimes prohibitively for multi-factor models. On the other hand, the GMM method of Hansen and Scheinkman (1982), which has been refined e.g. in Chan et al. (1992), is simple to implement, but not efficient. Ingram and Lee (2001); Duffie and Singleton (1993) develop a version of GMM whose moments are computed via simulations; this approach turns out to be useful when the moments are hard to compute, but its efficiency properties are unknown. Finally, Gallant and Tauchen (1996) develop a GMM estimator by selecting the moment conditions as the scores of an auxiliary model; these moments are computed via simulation, and if the auxiliary model encompasses, in a sense that will be more clear later, the true (structural) model, their method is as efficient as maximum likelihood: following these results, they named their method Efficient Method of Moments (henceforth EMM).

The aim of this paper is to select a model which should be able to fit the Italian time series of the short rate from 1981 to 2001. We identify the short rate as the yield of the three-months Italian Treasury Bills (named BOT). We perform our selection among models of the form (1.1); the proposed models differ from the choice of the parametric specifications of μ and σ , which are allowed to depend upon other Markov factors. To estimate these models, in the sea of estimators previously quoted, we adopt the EMM technique. Our choice is motivated essentially by two facts: the first is that, differently from other methods, a carefully implemented EMM estimation gains full efficiency; the efficiency of EMM is a well known theoretical and empirical fact. Second, EMM estimation provides, as a by-product, a battery of diagnostic specification tests, which are very useful in making selection among different models, which is exactly the aim of this paper.

EMM is now a well established method; other application on interest rate models include Ahn et al. (2002); Andersen and Lund (1997); Bansal and Zhou (2002); Dai and

Singleton (2000); Gallant and Tauchen (1998); Jensen (2000); Tauchen (1997). The method has also been used for estimating stock prices models (Andersen et al., 2002; Chernov et al., 2003; Craine et al., 2000; Gallant et al., 1999), currency models (Bansal et al., 1995; Chung and Tauchen, 2001) and assessing the relation of stock prices with option prices (Benzoni, 1999; Chernov and Ghysels, 2000; Jiang and van der Sluis, 1999). Our list is extensive but not exhaustive. We remark that the main results on the interest rate models have been obtained on U.S. data.

We test different models of the Italian short rate in the spirit of Andersen and Lund (1997); Gallant and Tauchen (1998). We start our search from one-factor models. Previous work on estimation of interest rate diffusion models, however, pointed out the fact that one-factor parameterizations are not able to express all the information included in the interest rate data (Pearson and Sun (1994) is a celebrated example). The main result of recent research on this subject is that at least a richer volatility parameterization is needed to obtain a good fit of the observed time series. We then extend our model to multi-factor models, and look for the most parsimonious representation of a diffusion model which embodies the statistical features of the Italian short rate.

In our paper, we make some simplifying assumptions. First, we do not specify market prices of risk in the estimation step. From this perspective, we regard the short rate as a variable generated by a diffusion process and discretely observed. Second, we do not make any attempt of linking our models to macro-economic variables, as for example in Piazzesi (2005)³. We clearly recognize the importance of incorporating news and macro-economic facts in the model, as the high interest rate level in the period 1979-1982 or the EMU transition in 1999, but we believe that a model which is free from these instances, even if it has the flaw of not assessing thoroughly the economic significance of the results, is simpler to implement for applications.

Our paper is structured in the following way. The parameter vectors of the structural models are estimated by finding the minimum of a chi-square criterion function, whose moments are the scores of the auxiliary model, which are computed via a simulation-based numerical approximation. This procedure and all its properties are illustrated in Section 2 where we also compare EMM with other estimation methodologies. We illustrate the SNP approach, which is the *projection* step in EMM estimation,

³On this topic there are many recent contributions. See Ang and Piazzesi (2003); Dewachter and Lyrio (2005); Diebold et al. (2005); Hordahl et al. (2003); Kozicki and Tinsley (2001, 2002, 2003); Rudebusch and Wu (2003). See also Balduzzi et al. (2001) and Fleming and Remolona (1999).

in Section 3. In the fourth and in the fifth Section we illustrate results of the application respectively of the SNP algorithm and of EMM on the Italian three-months BOT yields time series. The last section reports the conclusions of our work.

2. THE EMM ESTIMATOR

In this Section, we briefly review the main properties of the EMM estimation method; for a thorough review, see Gallant and Tauchen (2004) and the references therein.

2.1. Definition. The EMM estimation method starts with the need of an auxiliary model which should nest the structural one to achieve asymptotic efficiency; then the auxiliary model has to describe statistically the data in the most accurate way: the guidelines of the choice of the auxiliary model will be illustrated in Section 3.

Let us assume that the (parametric) transition density of the auxiliary model is given by $f(y_t|x_{t-1}, \theta)$, where θ denotes the parameter vector, $x_{t-1} = (y_{t-1}, \dots, y_{t-L})$ is a vector of L past lagged values. On the other side, we denote the (parametric) transition density of the structural model by $p(y_t|x_{t-1}, \rho)$, where ρ denotes the true parameter vector whose estimation is the aim of the whole procedure. By structural we mean that $p(y_t|x_{t-1}, \rho)$ is the true data generating process. Let us denote by \tilde{y}_t , $t = 1, \dots, n$ the vector of the observations. If $\tilde{\theta}$ is the maximum likelihood estimator of the auxiliary model:

$$(2.1) \quad \tilde{\theta} = \operatorname{argmax}_{\theta} \left\{ \frac{1}{n} \sum_{t=L+1}^n \log[f(\tilde{y}_t|\tilde{x}_{t-1}, \theta)] \right\},$$

then we have asymptotically (White, 1994):⁴

$$(2.2) \quad \tilde{\theta} \longrightarrow \theta^* = \operatorname{argmax}_{\theta} \int \log[f(y_t|x_{t-1}, \theta)] p(y_t, x_{t-1}|\rho_0) d(y_t, x_{t-1})$$

where ρ_0 is the true vector of parameters. The second member of equation (2.2) is the expected value, under the structural model transition density, of the log-likelihood of the auxiliary model. Thus, if we define the score function of the auxiliary model by:

$$(2.3) \quad s_f(y_t, x_{t-1}, \theta) = \frac{\partial}{\partial \theta} \log f(y_t|x_{t-1}, \theta)$$

⁴Let us recall that $p(y_t|x_{t-1}; \rho) = \frac{p(y_t, x_{t-1}; \rho)}{p(x_{t-1}; \rho)}$, where $p(y_t, x_{t-1}; \rho)$ is the unconditional density of (y_t, x_{t-1}) .

then from first order conditions we have asymptotically:

$$(2.4) \quad \int s_f(y_t, x_{t-1}, \theta^*) p(y_t, x_{t-1} | \rho_0) d(y_t, x_{t-1}) = 0.$$

This equation has to be fulfilled by the true parameter vector ρ_0 for any choice of the auxiliary model.

The idea of the EMM estimator is to find the parameter vector ρ_0 which satisfies (2.4). The main difficulty is that the integral in (2.4) cannot be computed if $p(y|x, \rho)$ is not given; nevertheless in most cases we can simulate the score of the auxiliary model by using a Monte Carlo numerical approximation based on the central limit theorem:

$$(2.5) \quad \frac{1}{N} \sum_{\tau=L+1}^N s_f(\hat{y}_\tau(\rho), \hat{x}_{\tau-1}(\rho), \tilde{\theta}) \simeq 0$$

where we denote by \hat{y} the simulated values from the structural model $p(y|x, \rho)$. If the length of the parameter vector θ is larger than the length of ρ , as it is usually the case, it is not possible to directly solve the system (2.5) in order to determine an estimate of ρ . It is instead straightforward to use the GMM method of Hansen and Scheinkman (1982), by simulating the scores of the auxiliary model. Thus the EMM estimator is:

$$(2.6) \quad \tilde{\rho} = \operatorname{argmin}\{\hat{m}(\rho, \tilde{\theta})' \tilde{I}_n^{-1} \hat{m}(\rho, \tilde{\theta})\}$$

where

$$(2.7) \quad \hat{m}(\rho, \tilde{\theta}) = \frac{1}{N} \sum_{\tau=L+1}^N s_f(\hat{y}_\tau(\rho), \hat{x}_{\tau-1}(\rho), \tilde{\theta})$$

$$(2.8) \quad \tilde{I}_n = \operatorname{Var} \left[\frac{1}{\sqrt{n}} \sum_{t=L+1}^n s_f(\tilde{y}_t, \tilde{x}_{t-1}, \tilde{\theta}) \right].$$

The variance-covariance matrix is also straightforward to compute:

$$(2.9) \quad \tilde{\Sigma}_{\tilde{\rho}} = \left[\left(\frac{\partial m(\tilde{\rho}, \tilde{\theta})}{\partial \rho} \right)' \tilde{I}_n^{-1} \left(\frac{\partial m(\tilde{\rho}, \tilde{\theta})}{\partial \rho} \right) \right]^{-1}.$$

2.2. Properties. The main properties of the EMM estimator are thoroughly discussed in Tauchen (1997) among others. First of all, $\tilde{\rho}$ is a *consistent* estimator of the parameter vector. Second, the EMM estimator has an *asymptotic normal distribution*, as a consequence of the fact that $\tilde{\theta}$ is a maximum likelihood estimator and that, therefore,

$$(2.10) \quad \sqrt{n}(\tilde{\theta} - \theta^*) \longrightarrow \mathcal{N}(0, H^{-1} I H^{-1})$$

where H is the Hessian matrix $\left(H_{ij} = \frac{\partial^2 \mathcal{L}}{\partial \theta_i \partial \theta_j}\right)$ of the log-likelihood function \mathcal{L} , while I is the Fisher information matrix. Most important, if the auxiliary model nests the structural model, EMM tends asymptotically to be as *efficient* as the maximum likelihood estimator (Gallant and Long, 1997). Finally, it is useful to point out the fact that values of ρ that belong to unstable or unacceptable regions of the parameter space cannot minimize the chi-square function and consequently be the result of the estimation process (Tauchen, 1997). This fact is illustrated in Andersen et al. (1999) by means of Monte Carlo experiments. It is suggested, instead, to check that $\tilde{\theta}$ makes the auxiliary model stable.

2.3. Diagnostics. One crucial feature which makes EMM appealing for model estimation and selection is the fact that it provides readily available diagnostics. Indeed, under the null hypothesis that the selected model is the true data generating process, the objective function (2.6) is distributed asymptotically as a chi-square:

$$(2.11) \quad n \cdot m(\tilde{\rho}, \tilde{\theta})' \tilde{I}_n^{-1} m(\tilde{\rho}, \tilde{\theta}) \longrightarrow \chi^2(l_\theta - l_\rho),$$

where l_θ is the length of the vector of parameters of the auxiliary model, while l_ρ is the length of the vector of parameters of the structural hypothetical model⁵.

Therefore, computing the value of the objective function in $\tilde{\rho}$ and in $\tilde{\theta}$ is a way of overall testing the goodness of fit of the structural model that has been estimated.

Let us denote by D_ρ the derivative operator with respect to ρ . I is again the Fisher information matrix. Starting from the fact that, if the structural model is the true data generating process, reminding that ρ_0 is the true parameter vector, we have (Tauchen, 1997):

$$(2.12) \quad \sqrt{nm}(\tilde{\rho}, \tilde{\theta}) \longrightarrow N(0, [I - D_{\rho_0}(D'_{\rho_0} I^{-1} D_{\rho_0})^{-1} D'_{\rho_0}]),$$

then an other readily obtained diagnostic is provided by the following T-statistic:

$$(2.13) \quad T_n = \left\{ \text{diag} \left[\tilde{I}_n - \tilde{D}_{\tilde{\rho}} (\tilde{D}'_{\tilde{\rho}} \tilde{I}_n^{-1} \tilde{D}_{\tilde{\rho}})^{-1} \tilde{D}'_{\tilde{\rho}} \right] \right\}^{-\frac{1}{2}} \sqrt{nm}(\tilde{\rho}, \tilde{\theta}).$$

which are asymptotically t -distributed. This statistic could be difficult to compute because $\tilde{D}'_{\tilde{\rho}} = \frac{\partial m(\tilde{\rho}, \tilde{\theta})}{\partial \rho'}$ needs to be estimated numerically. Simpler to compute, and thus useful in intermediate optimization steps, is

$$(2.14) \quad \tilde{T}_n = \left\{ \text{diag} \left[\tilde{I}_n \right] \right\}^{-\frac{1}{2}} \sqrt{nm}(\tilde{\rho}, \tilde{\theta})$$

⁵ \tilde{I}_n is the estimate of the Fisher information matrix.

which are also asymptotically t -distributed and are called *quasi t-ratios*. High values of the t -ratio (or quasi t -ratio) statistics for a given parameter would signal that the model specification is not able to account for that auxiliary model parameter.

2.4. Comparison with other methods. The EMM method of estimation could look just as a development of the so-called *indirect inference* that was introduced by Gourieroux et al. (1993). The two estimators are, instead, different. The indirect inference estimator is computed by solving the following optimization problem:

$$(2.15) \quad \hat{\rho}_{GMR} = \operatorname{argmin} \left[\hat{\theta}_N(\rho) - \tilde{\theta} \right]' \left[\tilde{H}^{-1} \tilde{I}_n \tilde{H}^{-1} \right]^{-1} \left[\hat{\theta}_N(\rho) - \tilde{\theta} \right]$$

where $\tilde{\theta}$ is the maximum likelihood estimator of the auxiliary model, while $\hat{\theta}_N$ is the maximum likelihood estimator that is found by simulating the log-likelihood starting from a vector of parameters ρ :

$$(2.16) \quad \hat{\theta}_N(\rho) = \operatorname{argmax} \frac{1}{N} \sum_{t=L+1}^N \log [f(\hat{y}_t(\rho) | \{\hat{y}_{t-\tau}\}_{\tau=1}^L, \theta)].$$

and \tilde{H} is an estimate of the Hessian matrix. It is clear that the method of indirect inference is more computationally complex than EMM, since for each possible value of ρ it has to solve a non-linear optimization problem for the simulated log-likelihood. Moreover the method of Gourieroux et al. (1993) needs to estimate the Hessian matrix at each step of the procedure, thus increasing the computational burden.

EMM is also different from the SMM method of Ingram and Lee (2001) and Duffie and Singleton (1993), which use simulation to compute the moments of the structural model, which are compared via GMM to the realized moments. EMM, instead, selects the moments as the scores of a suitably selected auxiliary model.

Many studies have been conducted to compare the properties of EMM with other estimation techniques, especially GMM. Indeed, all the above results hold for infinite samples, while for finite samples no results are available and one has to resort to Monte Carlo experiments. Gallant and Tauchen (1999) stress the fact that it is not possible to make direct comparison between indirect inference and EMM through Monte Carlo simulation, because we cannot use the same auxiliary model for the two methods. If we want to apply indirect inference we should select an easy to compute auxiliary model because we have to maximize the likelihood repeatedly. EMM requires, instead, the score generator to be a good approximation of the data distribution. On the other hand, comparisons can be made between EMM and the class of procedures that Gallant

and Tauchen (1999) classify as CMM (Classical Method of Moments), which includes the GMM estimator of Hansen and Scheinkman (1982) and SMM.

These authors find that EMM is generally more efficient than CMM, a result which is confirmed also by the analysis of Andersen et al. (1999); Chumacero (1997); Zhou (2001) also in small samples ($n = 500$), which is particularly interesting for our application, in which $n = 470$.⁶ Moreover EMM improves the strong over-rejection bias of GMM, while improving the rejection of misspecified models (Zhou, 2001). *Ad hoc* choice of moment conditions is probably the main reason of under-performance of GMM and SMM. In the framework of EMM, the weighting matrix is simpler to compute because the scores of a well fitted auxiliary model should be approximately orthogonal. Andersen et al. (1999) show that the t -statistics are well-behaved even in small samples. Regarding efficiency, the theoretical result of Gallant and Long (1997) is confirmed by Andersen et al. (1999): they evaluate EMM efficiency for samples of different size and they verify that asymptotically ($n = 4000$) EMM efficiency is very close to that of maximum-likelihood. Finally, Michaelides and Ng (2000) find, again by means of a Monte Carlo study in the context of the theory of storage, that EMM over-performs both indirect inference and SMM. Wu (2001) applies EMM to estimate a model for the leverage effect.

In general, we conclude that if the transition density is known maximum likelihood or quasi-maximum likelihood should be preferred with respect to EMM. In all other cases EMM provides a reasonable alternative.

3. THE SNP ALGORITHM

Selecting an auxiliary model that resumes the statistical properties of the observed data is the central condition for a good performance of EMM procedure.

The choice of the auxiliary model (sometimes referred to as projection), in fact, is tightly connected to the efficiency of EMM. The transition density used in the projection should closely approximate the distribution of the data. In the best case, if the auxiliary model encompasses the structural one, EMM is as efficient as maximum likelihood (Gallant and Long, 1997). Gallant and Tauchen (1989) proposed to use in

⁶In Andersen et al. (1999) it is shown that in small samples, the fit of an over-identified auxiliary model, as those used later in this paper, can be problematic since it often results in crashes or spurious fitting. They advocate, instead, close-to or perfectly identified moments. Since we do not experience such a problem, and this result is not confirmed by Chumacero (1997) and Zhou (2001), we guess that this effect strongly depends on the properties of the structural model.

this first step of the procedure an expanding class of conditional densities that they call SNP (Semi Non Parametric). The name SNP stems from the fact that, even if no a-priori hypothesis is done, the projection represents a process of selection among a family of parametric functions. To describe this class of densities we will let the process of interest $\{y_t\}_{t=-\infty}^{\infty}$ depend on an innovation $\{z_t\}_{t=-\infty}^{\infty}$ via:

$$(3.1) \quad y_t = R_x \cdot z_t + \mu_x,$$

where y , z and μ_x , the *location function*, are vectors of size M while R_x , the *scale function*, is an $M \times M$ upper triangular matrix obtained through Cholesky decomposition of the covariance matrix. The density of the innovation can be approximated through an Hermite expansion:

$$(3.2) \quad h(z) = \frac{P^2(z)\phi(z)}{\int_{\mathbb{R}^M} P^2(s)\phi(s)ds},$$

where P is the Hermite polynomial of degree K and ϕ is a standard Normal multivariate density. The polynomial is squared to guarantee a positive density. To obtain the density of the original process y we just need to apply the change of variables transformation rule:

$$(3.3) \quad f(y_t|x_{t-1}, \theta) = \frac{P^2[R_x^{-1}(y_t - \mu_x)]\phi[R_x^{-1}(y_t - \mu_x)]/|\det(R_x)|}{\int_{\mathbb{R}^M} P(s)^2\phi(s)ds}$$

where $\phi[R_x^{-1}(y_t - \mu_x)]/|\det(R_x)|$ is a Normal multivariate density, of argument y , with mean μ_x and variance-covariance matrix $\Sigma_x = R_x \cdot R_x'$, K is the degree of the polynomial P , while x_{t-1} is the vector of the past values of y . The parameter vector of this density, θ , is estimated via maximum likelihood⁷.

An important property of the Hermite expansion, which makes it a good way to approximate the data distribution, is that it represents a class of densities which encompasses a lot of important statistical models. More precisely, if we indicate with H_K the domain of all SNP densities, for any choice of R and μ , in which the degree of the P polynomial is K , the closure of the union $H = \cup_{K=1}^{\infty} H_K$ under a weighted Sobolev norm contains the density $p(y|x, \rho)$ (Gallant and Tauchen, 1998). Moreover

⁷More precisely, to avoid negative densities induced by the numerics, we fit

$$(3.4) \quad f_K(y_t|x_{t-1}, \theta) = \frac{\{P_K^2[R_x^{-1}(y_t - \mu_x)] + \epsilon_0\}\phi[R_x^{-1}(y_t - \mu_x)]/|\det(R_x)|}{\int_{\mathbb{R}^M} P_K^2(s)\phi(s)ds + \epsilon_0},$$

after setting $\epsilon_0 = 1 \cdot 10^{-5}$.

under conditions easy to be verified SNP defines a consistent (Gallant and Nychka, 1987) estimator of the structural transition density $p(y|x, \rho)$.

After modeling the distribution of the residuals, we specify R_x and μ_x to introduce dependence in the data. In particular we model μ_x as:

$$(3.5) \quad \mu_{x_{t-1}} = \psi_0 + \psi_1 y_{t-1} + \dots + \psi_{L_\mu} y_{t-L_\mu} = \psi_0 + \Psi x_{t-1},$$

where x_{t-1} is the vector of the L_μ lagged values of each y variable. The conditional heterogeneity of the stochastic process can be represented in the Hermite expansion by introducing a dependence on P coefficients from y_{t-1} . Following Gallant and Tauchen (1989), the transition density f becomes:

$$(3.6) \quad f(y_t|x_{t-1}, \theta) = \frac{\left[\sum_{|\alpha|=1}^{K_z} A_\alpha(y_{t-1}) R_x^{-1} (y_t - \psi_0 - \Psi x_{t-1})^\alpha \right]^2 n_M(y_t|\mu_x, \Sigma_x)}{\int \left[\sum_{|\alpha|=1}^{K_z} A_\alpha(y_{t-1}) u^\alpha \right]^2 \phi(u) du},$$

with

$$(3.7) \quad A_\alpha(y_{t-1}) = \sum_{|\beta|=0}^{K_x} A_{\alpha\beta} y_{t-1}^\beta.$$

To achieve identification A_{00} is set equal to one. We introduce conditional heteroscedasticity in the variance-covariance matrix Σ_x in the following way. Setting R_x as:

$$(3.8) \quad \begin{aligned} vech(R_x) &= p_0 + \sum_{i=1}^{L_r} P_i |y_{t-L_r+i} - \mu_{x_{t-1-L_r+i}}| \\ &+ \sum_{i=1}^{L_g} diag(G_i) vech(R_{x_{t-1-L_g+i}}). \end{aligned}$$

where $vech(R)$ is the vector obtained with all the upper triangular elements of R , p_0, P_i are vectors of length $M(M+1)/2$, $G(1)$ through $G(L_g)$ are vectors of length $M(M+1)/2$, we obtain a model similar to the GARCH model of Bollerslev (1986)⁸.

⁸The absolute value in (3.8) is not differentiable and, for this reason, it is substituted with a trigonometric approximation

$$(3.9) \quad a(u) = \begin{cases} (|100u| - \frac{\pi}{2} + 1)/100 & |100u| \geq \frac{\pi}{2} \\ (1 - \cos(100u))/100 & |100u| < \frac{\pi}{2} \end{cases}$$

In particular, if M is equal to one we can write

$$(3.10) \quad R_x = \tau_1 + \sum_{i=1}^{L_r} \tau_a(i) |y_{t-L_r+i} - \mu_{x_{t-1-L_r+i}}| + \sum_{i=1}^{L_g} \tau_g(i) R_{x_{t-1-L_g+i}}.$$

We remark that the just defined SNP model is still easily estimated via maximum likelihood.

Applying the SNP algorithm means choosing a particular member of the class of the Hermite expansion through a specification of $L_\mu, L_r, L_g, K_z, K_x$. The auxiliary model that we have just described is that proposed in Gallant and Tauchen (1989). Andersen and Lund (1997) and Andersen et al. (2002) use SNP in the projection step, but they parameterize the conditional variance via an E-GARCH specification (Nelson, 1991). Moreover they ask the auxiliary model to incorporate the asymmetric volatility effect.

We finally point out the fact that the use of SNP is legitimated also by Monte Carlo studies that have verified its properties, see e.g. Zhou (2001).

4. AN APPLICATION OF SNP ON ITALIAN SHORT INTEREST RATE TIME SERIES

As described in the previous section, we use the SNP algorithm to describe our data, performing a selection among a parametric family of transition densities whose maximum likelihood estimation is straightforward. The data set under study is the time series of the yields on three-month zero coupon bond issued twice per month by the Italian government (BOT, *Buoni Ordinari del Tesoro*), from September, 1981 to June 2001, for a total of 470 observations; we use the first 14 as a provision for initial lags; the time series evolution is plotted in Figure 1.⁹ We take the yield on the three-month yield as a proxy of the short rate, as it is common in many applications (Gallant and Tauchen, 1998; Andersen and Lund, 1997), see Chapman and Pearson (2001) for a discussion on the economic relevance of this choice. As it can be seen in Figure 1, the time series under study is sharply decreasing during the period at our disposal.¹⁰

⁹It is clear that our time series presents many structural breaks, the more evident being the transition to EMU in January, 1999. As an exercise, we re-estimated the auxiliary model on the time series up to 1998, and we obtained qualitatively identical results to those presented in the paper.

¹⁰On the basis of the result of the Augmented Dickey Fuller test, we cannot reject the null hypothesis of non stationarity at 95% confidence level (the test value is -2.2231 , while the correspondent critical value is -3.41). Nevertheless, in what follows, we assume that our data are a sub-sample of a stationary

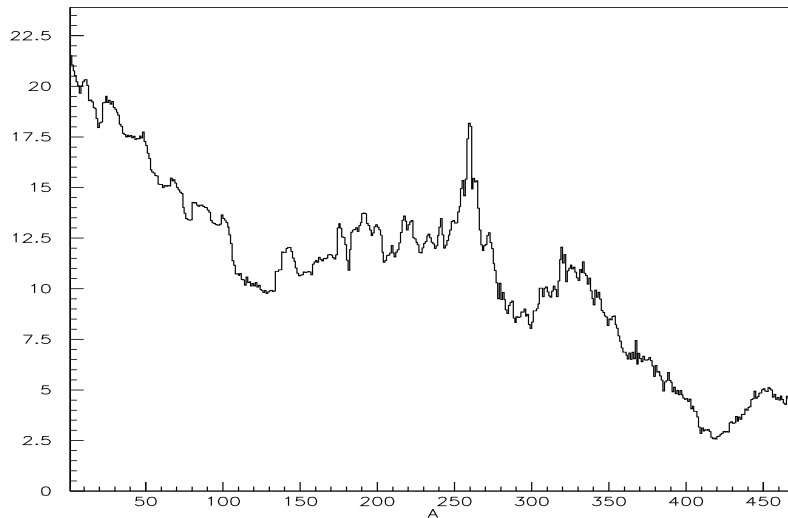


FIGURE 1. The time series under study.

The choice of the SNP model, as described in Section 3, is done via the choice of the lags $L_\mu, L_g, L_r, K_z, K_x$ that define an $AR(L_\mu) - SNP - GARCH(L_r, L_g) - P(K_z, K_x)$ model. Let us recall, in particular, that K_z is the degree of the rational polynomial P in (3.2), while K_x is the maximum degree of each polynomial coefficient $A_\alpha(y_{t-1})$ in (3.7). Several combinations of these parameters have been estimated¹¹. The goodness of the fit of a given model cannot be given simply by the maximum likelihood:

$$(4.1) \quad s_n(\tilde{\theta}) = -\frac{1}{n} \sum_{t=(L+1)}^n \log[f(\tilde{y}_t | \{\tilde{y}_{t-\tau}\}_{\tau=1}^L, \tilde{\theta})],$$

time series; for a colorful argument supporting this assumption see Cochrane (2001), p. 199. It is important to remark that in the continuous-time models studied here the dependent variable is a first difference, so the problem of stationarity is minor, see Chan et al. (1992). In a recent paper, also Bandi (2002) thoroughly discusses this topic.

¹¹Instead of using a branching tree, which could lead to miss some possible combinations, we preferred to estimate all the possible combinations, with $0 \leq L_\mu \leq 5, 0 \leq L_r, L_g \leq 2, 1 \leq K_z \leq 8, 0 \leq K_x \leq 1$

since increasing the number of parameters always improves the value of the log-likelihood. In order to introduce a penalty for over-parameterization, the usual technique is to consider the Schwarz-Bayes, Akaike, Hannan and Quinn information criteria, defined as:

$$(4.2) \quad \begin{aligned} BIC &= s_n(\tilde{\theta}) + \frac{1}{2}(p_\theta/n) \log(n) \\ AIC &= s_n(\tilde{\theta}) + p_\theta/n \\ HQC &= s_n(\tilde{\theta}) + (p_\theta/n) \log[\log(n)] \end{aligned}$$

where p_θ is the dimension of the parameter vector θ . The auxiliary density is chosen after considering the information criteria. Generally, it is not guaranteed that these different criteria provide the same indication.

Table 1 summarizes the results for the best 15 models according to the most popular BIC. In our case, the BIC criterion points towards 41160, while its second choice is 41180 and its third choice is 41140. HQC would select again 41160, then 51180 and 41180. Finally, AIC would select 51180 as the first choice, and 41160, 41180 as the second and third choice. The tendency of *AIC* to select over-fitted auxiliary models in small samples is well known, and has already been reported in the literature (Andersen and Lund, 1997). Then a natural choice would be 41160, which is selected by the other two criteria, and it is the second choice of *AIC*.¹²

Table 2 reports the parameter estimates, together with standard errors, for the 41160 model. All the parameters are highly significant, with the notable exceptions of the lag-zero auto-regressive specification. Let us note that odd coefficients of the Hermite polynomial have smaller *t*-statistics than even coefficients.

Few comments are in order. For all the best models, an high L_μ is found; the SNP-GARCH(1,1) parameterization is sufficient to fit the heteroscedasticity of the data; K_z is typically even (4, 6 or 8 are preferred); no need for heterogeneity is found ($K_x = 0$). These result are in line with Andersen and Lund (1997) and Jensen (2000) who analyze three-months Treasury Bills, while are quite different from those in Gallant and Tauchen (1998) on the three-months Treasury Bills, and Tauchen (1997), who analyzes 30-days Eurodollar interest rates. These authors use an ARCH parameterization instead of a GARCH-type one, and subsequently find heterogeneity ($K_x = 1$)

¹²Zhou (2001) suggests, via Monte Carlo evidence, to go beyond the first choice of BIC, since this criterion tends to under-fit the model, especially in small samples; in our case, we could select 41180, which is an unrestricted version of 41160. But the likelihood-ratio test value of these two nested models, which under the null is distributed as a χ^2 with 2 degrees of freedom, is $LR = 3.01$, thus we cannot reject the nested model at the 95% confidence level. On the other hand, the same test rejects 41140 with respect to 41160 ($LR = 22.3$).

TABLE 1. Reports the best 15 models obtained according to BIC; the first 5 columns report the parameterization, see the text; p_θ is the number of corresponding parameters; \mathcal{L} is the likelihood; AIC, HQC, BIC denote the information criteria (4.2); *Ljung-Box* reports the Ljung box statistics for the residuals with $p = 25$, divided by $25 - p_\theta$. *LB squared* reports the same for the squared residuals.

L_u	L_g	L_r	K_z	K_x	p_θ	$-2\log \mathcal{L}$	AIC	HQC	BIC	Ljung-Box	LB squared
4	1	1	6	0	14	-1173.5546	-1.2561	-1.2312	-1.1928	4.8057	1.4373
4	1	1	8	0	16	-1176.5671	-1.2550	-1.2265	-1.1827	5.9123	1.7937
4	1	1	4	0	12	-1151.8760	-1.2367	-1.2153	-1.1825	4.1496	1.1040
5	1	1	8	0	17	-1182.4436	-1.2593	-1.2290	-1.1824	5.5182	1.5866
3	1	1	6	0	13	-1157.0710	-1.2402	-1.2171	-1.1814	5.8176	1.2328
5	1	1	4	0	13	-1155.1705	-1.2381	-1.2150	-1.1794	3.7765	1.0568
5	1	1	7	0	16	-1173.5551	-1.2517	-1.2232	-1.1794	4.9238	1.2913
4	1	1	7	0	15	-1166.9220	-1.2466	-1.2199	-1.1788	5.6800	1.3927
3	2	1	6	0	14	-1159.1259	-1.2403	-1.2153	-1.1770	6.0774	1.4107
4	2	1	8	0	17	-1177.0916	-1.2534	-1.2231	-1.1765	6.6962	1.9830
3	1	1	4	0	11	-1139.9414	-1.2258	-1.2062	-1.1761	4.9101	1.1548
4	1	1	5	0	13	-1151.9662	-1.2346	-1.2115	-1.1758	4.4756	1.1949
3	1	1	7	0	14	-1155.5575	-1.2364	-1.2114	-1.1731	6.8800	1.3486
5	1	1	5	0	14	-1155.2095	-1.2360	-1.2110	-1.1727	2.8329	7.4629
5	1	1	3	0	12	-1142.7600	-1.2267	-1.2053	-1.1725	3.2457	1.0509

and low L_μ . Different specifications of the scale functions cannot be directly compared. Anyway, Jensen (2000) finds that the parsimonious GARCH(1,1) performs better than his best ARCH model, which is an ARCH(12). On the other hand, Andersen et al. (1999) find no substantial difference between GARCH and EGARCH specification with parsimonious models, especially in small samples.

As suggested in Gallant et al. (1993) and Andersen and Lund (1997), we ran specification tests using Ljung-Box statistic for the residuals and the squared residuals. The results on the best models, shown in Table 1, show that we were partially able to remove serial correlation in the residuals, while we were fully successful in removing serial correlation in the squared residuals.

Summarizing our results, the main features highlighted by the application of SNP algorithm on the Italian time series are that it presents a quite strong autoregressive component in the drift and persistence in volatility.

TABLE 2. Reports the fit of the $AR(4) - SNP - GARCH(1, 1) - P(6, 0)$ SNP model selected as a statistical description of the data. The parameters value are obtained via Maximum Likelihood. Standard errors are computed via outer product gradient (OPG).

Parameter	Estimate	Standard Error	t-statistic
A_{10}	-0.18400	0.09345	-1.969
A_{20}	-0.32189	0.06035	-5.334
A_{30}	0.08086	0.03511	2.303
A_{40}	0.07415	0.01722	4.307
A_{50}	-0.00722	0.00344	-2.099
A_{60}	-0.00406	0.00124	-3.284
ψ_0	-0.00045	0.00577	-0.079
ψ_4	0.15400	0.04203	3.664
ψ_3	-0.37898	0.05480	-6.916
ψ_2	0.17221	0.06745	2.553
ψ_1	1.04785	0.04870	21.517
τ_1	0.01423	0.00335	4.254
τ_a	0.36425	0.07256	5.020
τ_g	0.60637	0.07302	8.304

5. EMM ESTIMATES OF SHORT RATE DIFFUSION MODELS

In this section we estimate continuous-time diffusion models for the spot rate via EMM: we first check if one-factor models are flexible enough to capture the main properties of the Italian riskless bond yields; then we extend these models to multi-factor one. For all our applications, the simulated scores are computed with $N = 100,000$ draws, after discarding the first 1,000 to avoid strong dependence upon the arbitrary choice of the initial points. To simulate be-weekly observations, we simulate 24 observations per year, with 20 steps within two adjacent observations: we use an explicit second-order weak scheme to make the continuous-time diffusion discrete.

5.1. One factor models. Merton (1973) model is the first representation of continuous-time processes for the interest rate with Brownian motion disturbances. Now there is a rich specification of one-factor models, see Chan et al. (1992). We concentrate on

two very popular one-factor models: the Vasicek (1977) model:

$$(5.1) \quad dr_t = \alpha(\gamma - r_t)dt + \sigma dW_t.$$

and the CIR (Cox et al., 1985a,b) model:

$$(5.2) \quad dr_t = \alpha(\gamma - r_t)dt + \sigma\sqrt{r_t}dW_t.$$

These models are both mean-reverting processes; the difference is in the diffusion term; while the Vasicek model has Gaussian innovation, thus allowing for negative interest rates, the CIR model has a non-central chi-square transition density, which prevents the spot rate from becoming negative. The role of the parameters is economically straightforward to interpret. The parameter σ is proportional to the volatility of the process; γ is the long-run mean; α is the speed of mean reversion. Moreover the CIR model gives a mathematical representation of the so-called ‘level effect’: indeed empirically it is observed that volatility increases with the level of interest rates. This property cannot be explained by the Vasicek model. Both these models owe their popularity to the nice property that closed-form expressions for the transition density and bond prices are readily available. In what follows, we also deal with the unrestricted Chan et al. (1992) specification of one-factor models, the so-called constant elasticity of variance (CEV) model:

$$(5.3) \quad dr_t = \alpha(\gamma - r_t)dt + \sigma r_t^\xi dW_t.$$

An important feature of the selected one-factor models is that they present a linear drift, a property which is now a topic of debate in the literature: while both Ait-Sahalia (1996) and Stanton (1997) advocate a strong non-linearity in the drift, Chapman and Pearson (2000) show by Monte Carlo that this finding could depend on the fact that finite sample properties of the estimators adopted are not the same as asymptotic properties. They however do not conclude in favor of a linear drift, but just show that the rejection in Ait-Sahalia (1996) and Stanton (1997) is doubtful. In a recent study, also Christensen et al. (2001) reject a non-linear drift. Anyway, we will hold a linear drift throughout all our models, since in our opinion our data sample is too small to detect non-linearities in the drift¹³. The results of the estimates for one-factor models are reported in Table 3. The CIR and Vasicek model has been

¹³Since non-linearities in the drift would be detected by rare extremely high or extremely low events, Jones (2003) concludes that non-linearities cannot be detected even with the longest time series at our disposal, the 5000 observations long T-bill daily time series. This issue, anyway, is yet an open one.

TABLE 3. One-factor model estimates.

Vasicek model		
$\chi^2(11)$		37.511
Parameter	Estimate	95% confidence interval
α	0.032	(0.019, 0.084)
γ	6.22	(3.28, 8.34)
σ	1.15	(1.03, 1.29)
CIR model		
$\chi^2(11)$		37.766
Parameter	Estimate	95% confidence interval
α	0.1079	(0.1076, 0.1080)
γ	7.48	(7.47, 7.52)
σ	0.439	(0.438, 0.440)
CEV model		
$\chi^2(10)$		36.237
Parameter	Estimate	95% confidence interval
α	0.107	(0.103, 0.111)
γ	7.41	(7.30, 7.49)
σ	0.448	(0.438, 0.456)
ξ	0.493	(0.489, 0.505)

estimated through EMM several times on US short interest rate time series. In every case (Tauchen, 1997; Andersen and Lund, 1997; Gallant and Tauchen, 1998), they have been firmly rejected. We confirm this result on the Italian time series, also if the rejection is not so sharp: the χ^2 for CIR is nearly 37, which is low when compared with typical three-digits numbers obtained in similar studies: this is a consequence of the smallness of our data sample. Anyway, both one-factor models considered are rejected. The long-run mean is estimated to be around 6-7%, while the mean-reversion parameter

TABLE 4. Estimates for the CIR model parameters obtained via EMM and different methods. The column *naive* reports estimates based on a naive discretization of the continuous-time model. The maximum likelihood estimate is obtained using the inversion of the characteristic function (Singleton, 2001). The last column reports the estimates obtained cross-sectionally by Barone et al. (1991) using Italian bonds of all maturities for the period 1984-1990, and they are averages of daily estimates.

	EMM	<i>naive</i>	Maximum Likelihood	Barone, Cuoco, Zautzik (1991)
α	0.1079	0.141	0.256	0.243
γ	7.48	4.63	6.08	11.897
σ	0.439	0.564	0.537	0.619

is around 0.1: they are both quite low, but it is not surprising after looking at the time series under study, which displays very slow mean reversion and a decreasing shape. In order to assess the reliability of these results, we estimated the CIR model via a linear regression, after discretizing the continuous-time model to the first order,¹⁴ and via maximum likelihood, using the inversion of the characteristic function suggested in Singleton (2001). Moreover, we compared our results to those obtained by Barone et al. (1991), who analyzed Italian bonds of different maturities in the period 1984-1990, obtaining CIR estimates cross-sectionally. Table 4 shows the comparison: the estimates of the three parameters are reasonably the same across different approaches; only the long-run mean estimated by Barone et al. (1991) is considerably higher, but only because they analyzed interest rates in a period in which the interest rate level was higher. We then conclude that our estimates are reliable, and they show that the considered one-factor models are not able to fit the Italian data.

Extending to the CEV specification, no significant improvements in the chi-square are observed. The parameter ξ has been estimated several times in the literature. In their seminal work, Chan et al. (1992) estimated it around 1.5 on U.S. data, this result has been confirmed by Jones (2003) and Chan et al. (1992), while Eraker (2001);

¹⁴Gourieroux et al. (1993) point out that one of the main advantages in using simulation-based estimators is that of removing the bias involved by discretization. Moreover the same Authors show, via Monte Carlo evidence, that the discretization bias does not involve the mean reversion parameter.

Andersen and Lund (1997); Durham (2003); Christensen et al. (2001) find ξ to be much lower (around 0.7) and often not significantly different from the CIR value of 0.5. In our study on Italian data, we estimate ξ to be 0.492, and not statistically different from the CIR value.

Estimating one-factor models, we learned basically that other factors should be added to have a richer and more realistic parameterization. This is also consistent with the earlier finding of Litterman and Scheinkman (1991) that more factors are necessary to explain the observed realizations of the yield curve.

We remark that for misspecified models, as this is the case according to the χ^2 -test, it is not possible to do selection among different auxiliary models.

5.2. Two factor models. The need for multiple factors for the term structure has been advocated to explain the failure of one-factor models, a failure which is confirmed on the Italian short rate time series. We tried few specifications of two-factor models by specifying a diffusion process for the volatility parameter σ . We remark that σ plays a very different role in the CIR and Vasicek model, since the CIR model already incorporates a stochastic volatility specification through the \sqrt{r} in the diffusion term. We first tried the GARCH(1,1) continuous-time specification of Drost and Werker (1996), which is commonly used in applications describing the volatility of foreign exchange rate and stock prices, see e.g. Barucci and Renò (2002). This leads to the following two factor models, which we label GARCH-CIR:

$$(5.4) \quad \begin{aligned} dr_t &= \alpha(\gamma - r_t)dt + \sigma\sqrt{r_t}dW_{1t} \\ d\sigma^2 &= k(\omega - \sigma^2)dt + \lambda\sigma_t^2dW_{2t} \end{aligned}$$

where W_{1t} and W_{2t} are independent Brownian motions, and GARCH-Vasicek:

$$(5.5) \quad \begin{aligned} dr_t &= \alpha(\gamma - r_t)dt + \sigma dW_{1t} \\ d\sigma^2 &= k(\omega - \sigma^2)dt + \lambda\sigma_t^2dW_{2t} \end{aligned}$$

Volatility is parameterized as a mean-reverting process, a feature we will hold henceforth. Estimation results are reported in Table 5 and they show that the specifications (5.4),(5.5) provide quite a poor description of our data. The GARCH-CIR model does not notably improve the fit of the series: the chi-square decreases from 37 to only 34. The same is true for the GARCH-Vasicek model, thus these models are disappointingly similar to their one-factor counterparts. The literature on U.S. data (Gallant and Tauchen, 1998; Andersen and Lund, 1997) suggests instead to use a logarithmic specification for the mean-reverting volatility evolution, that proposed by Nelson (1991).

TABLE 5. Two-factor model estimates, with a GARCH specification of the variance.

GARCH-CIR model		
$\chi^2(9)$	34.774	
Parameter	Estimate	95% confidence interval
α	0.347	(0.326, 0.454)
γ	5.67	(5.59, 6.18)
ω	0.236	(0.233, 0.238)
κ	10.86	(10.85, 13.20)
λ	1.05	(0.73, 1.12)
GARCH-Vasicek model		
$\chi^2(9)$	34.719	
Parameter	Estimate	95% confidence interval
α	0.490	(0.487, 0.491)
γ	5.73	(5.71, 5.83)
ω	1.182	(1.179, 1.192)
κ	6.04	(6.02, 6.12)
λ	2.046	(2.033, 2.049)

With this model, remarkably good fits are obtained. Following their suggestion, we estimate the following models, which we label LOG-CIR:

$$(5.6) \quad \begin{aligned} dr_t &= \alpha(\gamma - r_t)dt + \sigma_t\sqrt{r_t}dW_{1t} \\ d\log\sigma_t &= k(\log\omega - \log\sigma_t)dt + \lambda dW_{2t} \end{aligned}$$

where again W_{1t} and W_{2t} are independent Brownian motions, and LOG-VASICEK:

$$(5.7) \quad \begin{aligned} dr_t &= \alpha(\gamma - r_t)dt + \sigma_t dW_{1t} \\ d\log\sigma_t &= k(\log\omega - \log\sigma_t)dt + \lambda dW_{2t} \end{aligned}$$

The results of the estimation process are reported in the Table 6. As for previous studies, the specifications (5.6),(5.7) provide a remarkably good fit of the time series. The χ^2 is indeed very low, so the LOG-CIR model cannot be rejected, and there is

no need for richer parameterization as in Andersen and Lund (1997) and Gallant and Tauchen (1998).

This is an important result: we find a model which gives a reasonable description of the data adding only two parameters to the one-factor counterparts. This finding also confirms results obtained in the literature on discrete models, which indicate that the EGARCH model has a performance superior to GARCH. On the other hand, this kind of model does not have desirable analytical properties, which motivates keeping on our research considering affine models.

Using a CEV specification instead of the CIR one does not improve notably the fit. We find $\xi = 0.336$, but it is important to remark that, since both the CEV model and the model with $\xi = 0.5$ are not rejected, we lack statistical power to detect differences on ξ .

5.3. Extending in the affine class. Affine models for diffusions deserve a special treatment, since, as shown in Duffie and Kan (1996), they provide closed form solutions for bond and derivative pricing¹⁵ at the cost of solving a system of ordinary Riccati differential equations, which can be solved with very fast, accurate and easily available algorithms, while different models need the solution of a partial differential equation, much harder to solve, even numerically. It is worth to note that CIR and Vasicek model are affine models, that is why a closed form solution exists.

We start by experimenting all possible two-factor affine models. As a second factor we can choose the mean, resulting in the AFFINE-MEAN model:

$$(5.8) \quad \begin{aligned} dr_t &= \alpha(\gamma_t - r_t)dt + \sigma\sqrt{r_t}dW_{1t} \\ d\gamma_t &= \theta(\nu - \gamma_t)dt + \eta\sqrt{\gamma_t}dW_{2t}, \end{aligned}$$

or the volatility, getting the AFFINE-VOL model:

$$(5.9) \quad \begin{aligned} dr_t &= \alpha(\gamma - r_t)dt + \sqrt{\sigma_t}dW_{1t} \\ d\sigma_t &= k(\omega - \sigma_t)dt + \lambda\sqrt{\sigma_t}dW_{2t} \end{aligned}$$

which can be extended to account for correlation among Brownian motions:

$$(5.10) \quad \begin{aligned} dr_t &= \alpha(\gamma - r_t)dt + \sqrt{\sigma_t}dW_{1t} + \rho_{\sigma r}\lambda\sqrt{\sigma_t}dW_{2t} \\ d\sigma_t &= k(\omega - \sigma_t)dt + \lambda\sqrt{\sigma_t}dW_{2t} \end{aligned}$$

Model (5.9) is the same as model (5.10) after setting $\rho_{\sigma r} = 0$. Estimation results, shown in Table 7, are not very encouraging. As for the GARCH models, the performance of

¹⁵In order to get this result the specification of the market price of risk cannot be arbitrary, see Duffee (2002); Dai and Singleton (2002).

TABLE 6. Two-factor model estimates, with a logarithmic specification of the variance.

LOG-CIR model		
$\chi^2(9)$		13.998
Parameter	Estimate	95% confidence interval
α	0.360	(0.359, 0.361)
γ	4.84	(4.82,4.85)
ω	0.4664	(0.4660, 0.4668)
κ	7.63	(7.59, 7.64)
λ	2.069	(2.067, 2.071)
LOG-Vasicek model		
$\chi^2(9)$		31.678
Parameter	Estimate	95% confidence interval
α	1.14	(1.11,1.24)
γ	6.69	(6.60,6.72)
ω	1.103	(1.091, 1.153)
κ	7.59	(7.57, 7.60)
λ	1.819	(1.811, 1.821)
LOG-CEV model		
$\chi^2(8)$		12.957
Parameter	Estimate	95% confidence interval
α	0.791	(0.787,0.793)
γ	6.06	(6.03,6.07)
ω	0.595	(0.592, 0.597)
κ	7.707	(7.699, 7.730)
λ	2.304	(2.303, 2.306)
ξ	0.336	(0.335, 0.338)

affine models is comparable to one-factor models, and there are no substantial differences in this failure if we use the mean as a second factor or the volatility. This finding motivates extending our specification to three-factor models. Three-factor affine models have been proposed earlier by Balduzzi et al. (1996) and Chen (1996), which were lead by the empirical finding of Litterman and Scheinkman (1991). Also Dai and Singleton (2000) find that three-factor models are necessary to obtain a reasonable model on U.S. data. We then test the BDFS model of Balduzzi et al. (1996), but we find disappointing results, as before. We then extend the BDFS model to allow for correlations between Brownian motions, towards the maximal model $A_{3,1}$ model in the sense of Dai and Singleton (2000):¹⁶

$$\begin{aligned}
 dr_t &= k_{rv}(\omega - \sigma_t)dt + \alpha(\gamma_t - r_t)dt + \sqrt{\sigma_t}dW_{1t} + \rho_{rs}\eta\sqrt{\sigma_t}dW_{2t} + \rho_{rg}\zeta dW_{3t} \\
 (5.11) \quad d\sigma_t &= \lambda(\omega - \sigma_t)dt + \eta\sqrt{\sigma_t}dW_{2t} \\
 d\gamma_t &= \nu(\mu - \gamma_t)dt + \zeta dW_{3t} + \rho_{gs}\eta\sqrt{\sigma_t}dW_{2t} + \rho_{gr}\sqrt{\sigma_t}dW_{1t}
 \end{aligned}$$

Results for this model are shown in Table 8. Even if twelve parameters have been used the chi-square statistic is only around 23, and consequently the model is rejected.

We conclude that, differently from the findings of Dai and Singleton (2000) on U.S. data, affine models, up to three-factors, are not able to provide a completely satisfactory statistical description of the Italian data.

It is worth looking at the t -ratios statistics (2.13) obtained on the main estimated models, which are reported in Table 9; in our case, they are not powerful enough to make selection among models. Anyway, they provide a (non significant) indication of the superior performance of the LOG-CIR model, since its t -ratios are systematically lower¹⁷.

5.4. Estimating the three-factor affine model via Kalman filter. In this subsection, we estimate the maximal affine model (5.11), with an alternative methodology, to check whether its disappointing performance is an artifact of the method of moments estimation procedure. We use maximum likelihood estimation via Kalman filter, since it turns out to be relatively simple for affine models.

¹⁶We cannot get the maximal model, because it has as many parameters as our SNP model

¹⁷As it is reported in Section 2.3, if the model specifications are able to account for auxiliary model parameters the t -ratios are asymptotically distributed as a t -Student.

TABLE 7. Two-factor affine model estimates.

AFFINE-VOL model		
$\chi^2(9)$		33.388
Parameter	Estimate	95% confidence interval
α	0.199	(0.091, 0.210)
γ	6.76	(6.63,6.88)
ω	1.450	(1.443, 1.457)
κ	2.55	(2.15, 2.61)
λ	0.933	(0.849, 0.941)
AFFINE-VOL model with correlation		
$\chi^2(8)$		30.732
Parameter	Estimate	95% confidence interval
α	0.180	(0.179,0.216)
γ	6.45	(6.34,6.58)
ω	1.455	(1.446, 1.465)
κ	2.46	(1.55, 2.59)
λ	0.909	(0.811, 0.923)
$\rho_{\sigma r}$	0.0024	(-0.0022,0.0067)
AFFINE-MEAN model		
$\chi^2(9)$		31.375
Parameter	Estimate	95% confidence interval
α	0.260	(0.259,0.261)
γ	6.07	(6.04,6.09)
ν	4.694	(4.686, 4.707)
θ	9.71	(9.67, 9.75)
η	9.89	(9.82, 10.02)

TABLE 8. Three-factor BDFS model estimates.

Extended BDFS model			
$\chi^2(6)$		23.467	
Parameter	Estimate	95% confidence interval	Kalman filter
k_{rv}	4.26	(-7.28, 10.39)	6.76
ω	0.44	(0.42, 0.49)	0.0251
α	3.95	(1.86, 5.17)	2.57
ν	3.35	(3.20, 3.54)	2.84
μ	4.13	(4.01, 4.25)	5.73
λ	1.04	(0.70, 1.12)	1.82
ρ_{rg}	0.49	(0.31, 0.66)	1.37
ζ	1.19	(0.83, 1.74)	2.98
ρ_{rs}	1.52	(1.45, 1.57)	1.52
η	0.6964	(0.6963, 0.6965)	4.58
ρ_{gs}	-2.37	(-7.09, -0.67)	-4.73
ρ_{gr}	-3.27	(-5.55, -2.91)	23.7

In the Kalman filter terminology (Harvey, 1989), our measurement equation for the model (5.11) is just:

$$(5.12) \quad y_t = r_t, \quad t = 1, \dots, n$$

since we observe the spot rate itself. This simplifies the forthcoming analysis.

Now, denoting by $X_t = (r_t, \sigma_t, \gamma_t)$ the triplet of the state variables, we can exploit the fact that the model (5.11) is affine to calculate the first two moments of X_t conditional on X_{t-1} , following Fackler (2000). These are still affine in X_{t-1} . Then we can write the transition equation as:

$$(5.13) \quad X_t = \psi_0 + \psi_1 X_{t-1} + \varepsilon_t$$

with $\varepsilon_t \sim \mathcal{N}(0, V)$ and $V = \phi_0 + \phi_1 X_{t-1}$, where $\psi_0(3 \times 1)$, $\psi_1(3 \times 3)$, $\phi_0(3 \times 3)$ and $\phi_1(3 \times 3 \times 3)$ are functions of the parameters, see Fackler (2000) for details.

The transition equation (5.13) is not the exact discretization of the process (5.11), since this is not Gaussian, then our estimation technique is quasi-maximum likelihood.

TABLE 9. T-ratios, \tilde{T}_n , for the main estimated models.

Parameter	CIR	AFFINE-VOL	LOG-CIR	Extended BDFS
A_{10}	-1.031	-1.521	-0.172	0.619
A_{20}	0.966	0.456	0.474	3.079
A_{30}	0.245	0.744	0.227	3.121
A_{40}	1.251	0.713	0.384	1.707
A_{50}	0.103	0.430	-0.191	1.657
A_{60}	0.561	0.055	0.191	-0.03
ψ_0	-0.357	-0.698	-0.267	-0.672
ψ_4	1.580	1.290	0.267	0.990
ψ_3	1.557	1.280	0.215	0.995
ψ_2	1.425	1.129	0.138	1.080
ψ_1	1.530	1.224	0.177	1.104
τ_1	0.435	-0.392	0.020	-0.221
τ_a	0.704	0.237	0.750	0.869
τ_g	0.429	-0.131	0.444	-0.211

Let $\hat{X}_{t|t-1}$ and \hat{X}_t denote the optimal mean square error estimators of X_t given the information at time $t - 1$ and t respectively. The Kalman filter provides their values. According to the prediction step:

$$(5.14) \quad \hat{X}_{t|t-1} = \psi_0 + \psi_1 \hat{X}_{t-1}$$

with mean square error matrix:

$$(5.15) \quad \Sigma_{t|t-1} = \phi_0 + \phi_1 \hat{X}_{t-1}$$

Then we can exploit the observation of $y_t = r_t$ in the update step:

$$(5.16) \quad \hat{X}_t = \hat{X}_{t|t-1} + \Sigma_{t|t-1} Z' \frac{y_t - Z \hat{X}_{t|t-1}}{F_t}$$

where $Z = (1, 0, 0)$, with mean square error matrix:

$$(5.17) \quad \Sigma_t = \Sigma_{t|t-1} \left(1 - \frac{\Sigma_{t|t-1}}{F_t} \right)$$

where:

$$(5.18) \quad F_t = Z \Sigma_{t|t-1} Z'$$

is a scalar in our model. Then quasi maximum likelihood can be computed as:

$$(5.19) \quad \log \mathcal{L} = c - \frac{1}{2} \sum_{t=1}^n \log |F_t| - \frac{1}{2} \sum_{t=1}^n \frac{(y_t - Z\hat{X}_{t|t-1})^2}{F_t}$$

where c is an irrelevant constant. Examples of this technique can be found in Babbs and Nowman (1999); Geyer and Pichler (1999); Lund (1997); Duan and Simonato (1999).

The estimate according to the Kalman filter are reported in Table 8. Qualitatively, they are very similar to those obtained via EMM, with the notable exceptions of the volatility specification, which has a lower mean ω and a larger volatility η , and ρ_{gr} which changes sign. We can test the specification of the model with the diagnostics on the residuals, defined as the standardized innovations $(y_t - Z\hat{X}_{t|t-1})/F_t^{1/2}$. The diagnostics still indicate severe misspecification. The Ljung-Box test at lag 5 is 14.64 and it is significant at 95% level. Jarque-Bera test for normality is 13.10, significant at 95% level. The ARCH effect test yields a t of 1.944, very close to the significance level at 95%, and a White-like test for heteroscedasticity yields a t on y_t^2 of 3.93.

Our conclusion is that the misspecification of the three-factor model is independent from the technique used for estimation.

6. CONCLUSIONS

In this work, we performed a horse-race between different diffusion models, with the aim of describing the evolution of the Italian short rate. In particular, this is the first application of EMM to Italian interest rate data.

In line with previous applications to U.S. data (Tauchen, 1997; Andersen and Lund, 1997; Gallant and Tauchen, 1998), we find that one-factor Vasicek and CIR diffusion models are not flexible enough to represent all the statistical information that is included in the Italian short rate time series.

We find evidence that a logarithmic specification of the variance, together with a CIR structure of the short rate volatility, is able to capture the main properties of the data, and it cannot be rejected on the basis of the statistical analysis.

On the other hand, all the other diffusions considered fail to describe the data according to the tests adopted. This is also true for affine models, which would be very appealing since they provide analytical bond and derivative pricing. Since the rejection of the three-factor affine model is quite surprising, we re-estimated the model with an alternative methodology based on the Kalman filter. Our results indicate that the misspecification does not depend on the estimation technique adopted.

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NON-TECHNICAL SUMMARY

The aim of this paper is to find the diffusion model which best fits the Italian short rate data. For the estimation technique, we adopt a refined version of the method of moments, that is the *Efficient methods of moments* (EMM henceforth), for several reasons. First of all standard econometric techniques, based on the short rate transition density, are computational cumbersome to apply, and often they are not even feasible. EMM, instead, has been introduced specifically to overcome typical problems in the estimation of diffusion models. Second, it has a lot of remarkable features: it is consistent, asymptotically Normally distributed and efficient. Finally, EMM provides as a by-product diagnostic tests that allow to compare the goodness of fit of different models. We consider several short rate diffusion specifications. One-factor models (CIR, Vasicek, CEV), have the worst performance: in line with the interest rate literature we find that a single state variable is not able to represent the short rate dynamics. As a consequence, we estimate also two-factor models adding an other state variable: the short rate volatility. We find that, while the popular GARCH specification does not improve significantly over one-factor models, modelling the logarithm instead of the square of the volatility leads to the best result. The log-CIR and the log-Vasicek specifications cannot, indeed, be rejected on the basis of EMM diagnostics and provide a remarkably good fit of the time series. Surprisingly, instead, the two and three-factor affine models do not perform well. We estimate affine models also via Kalman filter to verify that our result is not due to the implementation of EMM, and we confirm the poor performance of affine models. Our conclusions can then be summarized as follows. The two-factor models with logarithmic specification of volatility (log-Vasicek and log-CIR) provide the best fit to the data, while one-factor models, and two-factor models with different specification of volatility (GARCH and affine) are not able to explain the Italian short-rate dynamics.